

Hornsea Project Four: Environmental Statement (ES)

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Volume A4, Annex 4.5: Subsea Noise Technical Report Part 2

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5 Impact Piling Noise Modelling Outputs

5.1 Unweighted subsea noise modelling

- 5.1.1.1 This section presents the unweighted noise level results (i.e. in the absence of any frequency weighting applied for hearing sensitivity) from the modelling undertaken for impact piling operations using the parameters detailed in Section 2.2.2.
- 5.1.1.2 The following figures present unweighted SPL_{peak} and SEL_{ss} noise levels from impact piling operations at the modelling locations at Hornsea Four illustrated in Figure 6. Figure 7 to Figure 14 show the unweighted SPL_{peak} and SEL_{ss} for monopiles and pin piles for the maximum design and most-likely installation scenarios discussed in Section 4.3.
- 5.1.1.3 Comparing these plots shows that, in general, the increased noise levels are expected to occur in deeper water, for example the Outer Silver Pit to the east of the Hornsea Four array area (as shown in Figure 4). The effect of the differing water depths on noise transmission is also shown at greater distances to the north west of the site, where more "jagged" contours occur over the shallow areas and deeper channels.
- 5.1.1.4 Due to the transient nature of impact piling noise, the impulsive noise introduced to the water will return to background levels within seconds of the impulse passing. The SPL_{peak} and SEL_{ss} outputs shown on these plots should not be confused with background or ambient noise levels, which are typically described in terms of SPL_{RMS}. The different metrics are not directly comparable.
- 5.1.1.5 Level vs range plots are presented in **Figure 15** showing the noise levels from a deep water transect for both monopiles and pin piles giving the highest noise levels at range. These are 316° from the NW modelling location using the maximum design parameters.







































































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Figure 15: Level vs. range plots showing the unweighted SPL_{peak} and SEL_{ss} noise levels along one of the longest predicted transects; 316° from the NW modelling location using the maximum design parameters.

5.2 Noise modelling results in respect of marine mammal and fish impact criteria

5.2.1 Introduction

5.2.1.1 This section presents the modelling results in terms of noise metrics and criteria covered in Section 2.2. This discussion will guide the assessment of environmental impact from the predicted impact piling noise on marine species (see Volume A2, Chapter 3: Fish and Shellfish Ecology and Volume A2, Chapter 4: Marine Mammals). For all the results given in the following sections, ranges calculated to be less than 50 m for single strike criteria and 100 m for cumulative criteria have not been included due to the uncertainty in the accuracy of the results at such close range. In this case, the ranges are given as "< 50 m" or "< 100 m," indicating that the impact range will be within this distance.

5.2.2 Marine mammal criteria

- 5.2.2.1 This section presents the modelling results in biological terms for various species of marine mammals using the Southall et al. (2019) guidance. Interpretation of these modelling results are provided in Volume A2, Chapter 4: Marine Mammals. As discussed in paragraph 2.2.2.12, for the SEL_{cum} criteria, fleeing animal speeds of 3.25 ms⁻¹ (Blix and Folkow 1995) for LF cetaceans and 1.5 ms⁻¹ (Otani et al. 2000) for other species of marine mammal have been used. It should be reiterated that the marine mammal naming terminology used by Southall et al. (2019) is different to that used by NMFS (2018) and Southall et al. (2007), in that the former MF and HF categories are now effectively presented as HF and VHF, respectively.
- 5.2.2.2 **Table 13** to **Table 44** present the predicted PTS and TTS impact ranges for the different marine mammal hearing groups using the Southall et al. (2019) thresholds. The criteria are given as unweighted SPL_{peak} or weighted SEL_{cum} based on the hearing sensitivity of the receptor. Multiple pulse (SEL_{cum}) includes the noise exposure to a fleeing animal receptor over the entire installation period. In addition, instantaneous SPL_{peak} values for the first strike of each scenario have been given. **Volume A2, Chapter 4: Marine Mammals** provides an assessment of behavioural disturbance in marine mammals based on dose-response curves and the 5 dB increment SEL_{ss} contours shown above in **Figure 7** to **Figure 14**.
- 5.2.2.3 Further to this, impact ranges for three pin piles installed consecutively in a single 24-hour period at the NW location are given in Table 45 to Table 48. When considering a fleeing animal, the addition of two extra piling scenarios does not have a great effect on impact



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ranges as, following the first pile, the animal will have reached a distance where the noise is of a much lower level and thus contributes a relatively low additional exposure.

- 5.2.2.4 There is also the potential for piling to occur at two locations concurrently under the maximum design scenario. This modelling scenario is covered in depth and is presented in Section 5.3.
- 5.2.2.5 In line with the unweighted results shown in Section 5.1, the largest predicted ranges occur over the deeper water areas and transects with maximum SEL_{cum} PTS ranges of 11 km for LF cetaceans for monopiles and 12 km for VHF cetaceans for pin piles. The larger impact ranges for pin piles for HF and VHF cetaceans are also caused by the frequencies filtered by the Southall et al. (2019) species group weightings (Table 2 and Table 3); this is discussed further in paragraphs 5.2.2.6 to 5.2.2.9 after the results tables.

<u>Impact ranges – maximum design monopile</u>

Table 13: Summary of the SPL_{peak} Southall et al. (2019) PTS impact ranges for the four modelling locations considering the maximum design monopile input parameters.

Southall et al. (2019) – PTS		Maximum design – Monopile (5,000 kJ) / Impulsive criteria				
Unweig	hted SPL _P	eak	Area	Maximum range	Minimum range	Mean range
NW	LF	219 dB	0.06 km²	140 m	140 m	140 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	25 km²	2.9 km	2.8 km	2.8 km
	PCW	218 dB	0.09 km ²	170 m	170 m	170 m
E	LF	219 dB	0.06 km²	140 m	140 m	140 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	25 km²	2.9 km	2.7 km	2.8 km
	PCW	218 dB	0.09 km ²	170 m	170 m	170 m
S	LF	219 dB	0.04 km ²	120 m	120 m	120 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	16 km²	2.3 km	2.3 km	2.3 km
	PCW	218 dB	0.06 km²	140 m	140 m	140 m
HVAC	LF	219 dB	0.06 km²	140 m	140 m	140 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	25 km²	2.8 km	2.8 km	2.8 km
	PCW	218 dB	0.09 km ²	170 m	170 m	170 m

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Table 14: Summary of the SPL_{peak} Southall et al. (2019) TTS impact ranges for the four modelling locations considering the maximum design monopile input parameters.

Southall et al. (2019) – TTS		Maximum design — Monopile (5,000 kJ) / Impulsive criteria				
Unweig	hted SPL _P	peak	Area	Maximum range	Minimum range	Mean range
NW	LF	213 dB	0.57 km ²	430 m	430 m	430 m
	HF	224 dB	< 0.01 km²	60 m	50 m	60 m
	VHF	196 dB	130 km²	6.6 km	6.3 km	6.5 km
	PCW	212 dB	0.82 km ²	510 m	510 m	510 m
E	LF	213 dB	0.57 km ²	430 m	430 m	430 m
	HF	224 dB	< 0.01 km²	60 m	50 m	60 m
	VHF	196 dB	130 km²	7.0 km	6.0 km	6.5 km
	PCW	212 dB	0.82 km ²	510 m	510 m	510 m
S	LF	213 dB	0.39 km ²	360 m	350 m	350 m
	HF	224 dB	< 0.01 km²	50 m	50 m	50 m
	VHF	196 dB	80 km²	5.2 km	5.0 km	5.1 km
	PCW	212 dB	0.56 km²	430 m	420 m	430 m
HVAC	LF	213 dB	0.57 km²	430 m	430 m	430 m
	HF	224 dB	< 0.01 km²	60 m	50 m	60 m
	VHF	196 dB	130 km²	6.4 km	6.3 km	6.3 km
	PCW	212 dB	0.82 km ²	510 m	510 m	510 m

Table 15: Summary of the impulsive SEL_{cum} Southall et al. (2019) PTS impact ranges for the four modelling locations considering the maximum design monopile input parameters assuming a fleeing receptor.

Southall et al. (2019) – PTS		Maximum design – Monopile (5,000 kJ) / Impulsive criteria				
Weight	ed SEL _{cum}		Area	Maximum range	Minimum range	Mean range
NW	LF	183 dB	66 km²	6.9 km	3.7 km	4.5 km
	HF	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	155 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
E	LF	183 dB	76 km²	11 km	1.6 km	4.3 km
	HF	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	155 dB	0.09 km ²	450 m	< 100 m	100 m
	PCW	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
S	LF	183 dB	5.6 km²	2.5 km	< 100 m	1.0 km
	HF	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	155 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
HVAC	LF	183 dB	65 km²	5.8 km	3.5 km	4.5 km
	HF	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	155 dB	< 0.01 km ²	< 100 m	< 100 m	< 100 m
	PCW	185 dB	< 0.01 km²	< 100 km²	< 100 m	< 100 m

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Table 16: Summary of the impulsive SEL_{cum} Southall et al. (2019) TTS impact ranges for the four modelling locations considering the maximum design monopile input parameters assuming a fleeing receptor.

Southall et al. (2019) – TTS		Maximum design – Monopile (5,000 kJ) / Impulsive criteria				
Weight	ed SEL _{cum}		Area	Maximum range	Minimum range	Mean range
NW	LF	168 dB	2200 km ²	36 km	21 km	26 km
	HF	170 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	140 dB	860 km²	20 km	15 km	17 km
	PCW	170 dB	670 km ²	18 km	13 km	15 km
Е	LF	168 dB	1800 km²	42 km	16 km	23 km
	HF	170 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	140 dB	810 km²	25 km	12 km	16 km
	PCW	170 dB	640 km ²	22 km	10 km	14 km
S	LF	168 dB	1200 km²	27 km	13 km	19 km
	HF	170 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	140 dB	460 km ²	15 km	9.4 km	12 km
	PCW	170 dB	340 km ²	13 km	8.2 km	10 km
HVAC	LF	168 dB	1800 km²	32 km	16 km	24 km
	HF	170 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	140 dB	840 km ²	19 km	14 km	16 km
	PCW	170 dB	660 km ²	17 km	12 km	14 km

Table 17: Summary of the non-impulsive SEL_{cum} Southall et al. (2019) PTS impact ranges for the four modelling locations considering the maximum design monopile input parameters assuming a fleeing receptor.

Southall et al. (2019) – PTS		Maximum design – Monopile (5,000 kJ) / Non-impulsive criteria				
Weight	ed SEL _{cum}		Area	Maximum range	Minimum range	Mean range
NW	LF	199 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	HF	198 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	173 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	201 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
E	LF	199 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	HF	198 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	173 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	201 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
S	LF	199 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	HF	198 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	173 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	201 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
HVAC	LF	199 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	HF	198 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	173 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	201 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m

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Table 18: Summary of the non-impulsive SEL_{cum} Southall et al. (2019) TTS impact ranges for the four modelling locations considering the maximum design monopile input parameters assuming a fleeing receptor.

Southall et al. (2019) – TTS		Maximum design — Monopile (5,000 kJ) / Non-impulsive criteria				
Weight	ed SEL _{cum}		Area	Maximum range	Minimum range	Mean range
NW	LF	179 dB	300 km ²	13 km	8.4 km	9.8 km
	HF	178 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	153 dB	5.3 km ²	1.7 km	1.0 km	1.3 km
	PCW	181 dB	11 km²	2.3 km	1.6 km	1.8 km
E	LF	179 dB	290 km ²	18 km	5.4 km	9.0 km
	HF	178 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	153 dB	7.7 km ²	2.7 km	380 m	1.3 km
	PCW	181 dB	14 km²	3.4 km	800 m	1.9 km
S	LF	179 dB	97 km ²	8.0 km	3.2 km	5.3 km
	HF	178 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	153 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	181 dB	< 0.01 km²	170 m	< 100 m	< 100 m
HVAC	LF	179 dB	290 km²	12 km	7.3 km	9.6 km
	HF	178 dB	< 0.01 km²	< 100 m	< 100 m	<100 m
	VHF	153 dB	4.5 km ²	1.4 km	1.1 km	1.2 km
	PCW	181 dB	9.5 km ²	1.9 km	1.6 km	1.7 km

Table 19: Summary of the SPL_{peak} Southall et al. (2019) PTS impact ranges for the four modelling locations for the initial piling strike considering the maximum design monopile input parameters.

Southall et al. (2019) – PTS		Maximum design – Monopile, first strike (1,000 kJ) / Impulsive criteria				
Unweig	hted SPL _P	peak	Area	Maximum range	Minimum range	Mean range
NW	LF	219 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	1.7 km²	740 m	740 m	740 m
	PCW	218 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
E	LF	219 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	1.7 km²	740 m	740 m	740 m
	PCW	218 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
S	LF	219 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	1.1 km²	600 m	590 m	590 m
	PCW	218 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
HVAC	LF	219 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	1.7 km ²	740 m	740 m	740 m
	PCW	218 dB	< 0.01 km ²	< 50 m	< 50 m	< 50 m

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Table 20: Summary of the SPL_{peak} Southall et al. (2019) TTS impact ranges for the four modelling locations for the initial piling strike considering the maximum design monopile input parameters.

Southall et al. (2019) – TTS		Maximum design – Monopile, first strike (1,000 kJ) / Impulsive criteria				
Unweig	hted SPL	peak	Area	Maximum range	Minimum range	Mean range
NW	LF	213 dB	0.03 km ²	100 m	100 m	100 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	13 km²	2.1 km	2.1 km	2.1 km
	PCW	212 dB	0.04 km ²	120 m	120 m	120 m
Е	LF	213 dB	0.03 km ²	100 m	100 m	100 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	13 km²	2.1 km	2.0 km	2.1 km
	PCW	212 dB	0.04 km ²	120 m	120 m	120 m
S	LF	213 dB	0.02 km ²	80 m	80 m	80 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	8.4 km ²	1.6 km	1.6 km	1.6 km
	PCW	212 dB	0.03 km²	100 m	90 m	100 m
HVAC	LF	213 dB	0.03 km ²	100 m	100 m	100 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	13 km²	2.1 km	2.1 km	2.1 km
	PCW	212 dB	0.04 km ²	120 m	120 m	120 m

Impact ranges – maximum design pin pile

Table 21: Summary of the SPL_{peak} Southall et al. (2019) PTS impact ranges for the four modelling locations considering the maximum design pin pile input parameters.

Southall et al. (2019) – PTS		Maximum design – Pin pile (3,000 kJ) / Impulsive criteria				
Unweig	hted SPL	peak	Area	Maximum range	Minimum range	Mean range
NW	LF	219 dB	0.03 km ²	100 m	100 m	100 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	13 km²	2.1 km	2.0 km	2.1 km
	PCW	218 dB	0.04 km ²	120 m	120 m	120 m
E	LF	219 dB	0.03 km ²	100 m	100 m	100 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	13 km²	2.1 km	2.0 km	2.0 km
	PCW	218 dB	0.04 km ²	120 m	120 m	120 m
S	LF	219 dB	0.02 km ²	80 m	80 m	80 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	8.6 km ²	1.7 km	1.7 km	1.7 km
	PCW	218 dB	0.03 km ²	100 m	100 m	100 m
HVAC	LF	219 dB	0.03 km ²	100 m	100 m	100 m
	HF	230 dB	< 0.01 km²	< 50 km²	< 50 m	< 50 m
	VHF	202 dB	13 km²	2.1 km	2.1 km	2.1 km
	PCW	218 dB	0.04 km ²	120 m	120 m	120 m



Table 22: Summary of the SPL_{peak} Southall et al. (2019) TTS impact ranges for the four modelling locations considering the maximum design pin pile input parameters.

Southall et al. (2019) – TTS		Maximum design – Pin pile (3,000 kJ) / Impulsive criteria				
Unweig	hted SPL	peak	Area	Maximum range	Minimum range	Mean range
NW	LF	213 dB	0.27 km ²	300 m	300 m	300 m
	HF	224 dB	< 0.01 km ²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	79 km ²	5.1 km	4.9 km	5.0 km
	PCW	212 dB	0.39 km ²	360 m	360 m	360 m
E	LF	213 dB	0.27 km ²	300 m	290 m	300 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	78 km ²	5.4 km	4.7 km	5.0 km
	PCW	212 dB	0.39 km ²	360 m	350 m	360 m
S	LF	213 dB	0.18 km²	240 m	240 m	240 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	48 km ²	4.0 km	3.9 km	3.9 km
	PCW	212 dB	0.27 km ²	290 m	290 m	290 m
HVAC	LF	213 dB	0.27 km ²	300 m	300 m	300 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	76 km²	5.0 km	4.9 km	4.9 km
	PCW	212 dB	0.4 km ²	360 m	360 m	360 m

Table 23: Summary of the impulsive SEL_{cum} Southall et al. (2019) PTS impact ranges for the four modelling locations considering the maximum design pin pile input parameters assuming a fleeing receptor.

Southall et al. (2019) – PTS		Maximum design — Pin pile (3,000 kJ) / Impulsive criteria				
Weight	ed SEL _{cum}		Area	Maximum range	Minimum range	Mean range
NW	LF	183 dB	42 km ²	5.8 km	2.9 km	3.6 km
	HF	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	155 dB	160 km²	8.8 km	6.6 km	7.2 km
	PCW	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
E	LF	183 dB	53 km²	9.2 km	930 m	3.5 km
	HF	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	155 dB	170 km²	12 km	4.9 km	7.2 km
	PCW	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
S	LF	183 dB	1.5 km²	1.5 km	< 100 m	440 m
	HF	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	155 dB	51 km²	5.0 km	3.3 km	4.0 km
	PCW	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
HVAC	LF	183 dB	41 km²	4.7 km	2.7 km	3.6 km
	HF	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	155 dB	160 km²	7.9 km	6.6 km	7.2 km
	PCW	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m

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Table 24: Summary of the impulsive SEL_{cum} Southall et al. (2019) TTS impact ranges for the four modelling locations considering the maximum design pin pile input parameters assuming a fleeing receptor.

Southall et al. (2019) – TTS		Maximum design – Pin pile (3,000 kJ) / Impulsive criteria				
Weight	ed SEL _{cum}		Area	Maximum range	Minimum range	Mean range
NW	LF	168 dB	2000 km²	35 km	20 km	25 km
	HF	170 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	140 dB	2500 km²	36 km	24 km	28 km
	PCW	170 dB	480 km²	15 km	ll km	12 km
Е	LF	168 dB	1600 km²	40 km	15 km	22 km
	HF	170 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	140 dB	2100 km²	42 km	19 km	25 km
	PCW	170 dB	470 km²	19 km	8.9 km	12 km
S	LF	168 dB	1000 km²	26 km	12 km	18 km
	HF	170 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	140 dB	1400 km²	29 km	16 km	21 km
	PCW	170 dB	220 km²	10 km	6.8 km	8.4 km
HVAC	LF	168 dB	1700 km²	31 km	15 km	23 km
	HF	170 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	140 dB	2200 km ²	33 km	20 km	26 km
	PCW	170 dB	480 km ²	14 km	11 km	12 km

Table 25: Summary of the non-impulsive SEL_{cum} Southall et al. (2019) PTS impact ranges for the four modelling locations considering the maximum design pin pile input parameters assuming a fleeing receptor.

Southall et al. (2019) – PTS		Maximum design – Pin pile (3,000 kJ) / Non-impulsive criteria				
Weight	ed SEL _{cum}		Area	Maximum range	Minimum range	Mean range
NW	LF	199 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	HF	198 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	173 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	201 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
E	LF	199 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	HF	198 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	173 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	201 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
S	LF	199 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	HF	198 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	173 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	201 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
HVAC	LF	199 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	HF	198 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	173 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	201 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m

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Table 26: Summary of the non-impulsive SEL_{cum} Southall et al. (2019) TTS impact ranges for the four modelling locations considering the maximum design pin pile input parameters assuming a fleeing receptor.

Southall et al. (2019) – TTS		Maximum design – Pin pile (3,000 kJ) / Non-impulsive criteria				
Weight	ed SEL _{cum}		Area	Maximum range	Minimum range	Mean range
NW	LF	179 dB	240 km ²	12 km	7.5 km	8.7 km
	HF	178 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	153 dB	290 km ²	12 km	8.7 km	9.6 km
	PCW	181 dB	0.44 km ²	640 m	140 m	360 m
Е	LF	179 dB	240 km ²	17 km	4.7 km	8.1 km
	HF	178 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	153 dB	290 km²	15 km	6.7 km	9.4 km
	PCW	181 dB	1.7 km²	1.4 km	< 100 m	510 m
S	LF	179 dB	67 km²	6.8 km	2.5 km	4.4 km
	HF	178 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	153 dB	110 km²	7.4 km	4.9 km	6.0 km
	PCW	181 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
HVAC	LF	179 dB	230 km²	llkm	6.6 km	8.6 km
	HF	178 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	153 dB	290 km ²	llkm	8.7 km	9.6 km
	PCW	181 dB	0.24 km ²	380 m	210 m	280 m

Table 27: Summary of the SPL_{peak} Southall et al. (2019) PTS impact ranges for the four modelling locations for the initial piling strike considering the maximum design pin pile input parameters.

Southall et al. (2019) – PTS		Maximum design – Pin pile, first strike (600 kJ) / Impulsive criteria				
Unweig	hted SPL _P	eak	Area	Maximum range	Minimum range	Mean range
NW	LF	219 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	0.45 km²	380 m	380 m	380 m
	PCW	218 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
E	LF	219 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	0.45 km ²	380 m	380 m	380 m
	PCW	218 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
S	LF	219 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	0.29 km ²	310 m	310 m	310 m
	PCW	218 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
HVAC	LF	219 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	0.45 km ²	380 m	380 m	380 m
	PCW	218 dB	< 0.01 km ²	< 50 m	< 50 m	< 50 m

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Table 28: Summary of the SPL Southall et al. (2019) TTS impact ranges for the four modelling
locations for the initial piling strike considering the maximum design pin pile input parameters.

Southall et al. (2019) – TTS		Maximum design – Pin pile, first strike (600 kJ) / Impulsive criteria				
Unweig	hted SPL	peak	Area	Maximum range	Minimum range	Mean range
NW	LF	213 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	3.9 km ²	1.1 km	1.1 km	1.1 km
	PCW	212 dB	< 0.01 km²	60 m	60 m	60 m
E	LF	213 dB	< 0.01 km²	50 m	50 m	50 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	3.9 km ²	1.1 km	1.1 km	1.1 km
	PCW	212 dB	< 0.01 km²	60 m	60 m	60 m
S	LF	213 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	2.5 km ²	900 m	890 m	890 m
	PCW	212 dB	< 0.01 km²	50 m	50 m	50 m
HVAC	LF	213 dB	< 0.01 km²	50 m	50 m	50 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	3.9 km ²	1.1 km	1.1 km	1.1 km
	PCW	212 dB	< 0.01 km ²	60 m	60 m	60 m

Impact ranges – most likely monopile

Table 29: Summary of the SPL_{peak} Southall et al. (2019) PTS impact ranges for the four modelling locations considering the most likely monopile input parameters.

Southall et al. (2019) – PTS		Most likely – Monopile (4,000 kJ) / Impulsive criteria				
Unweig	hted SPL	peak	Area	Maximum range	Minimum range	Mean range
NW	LF	219 dB	0.04 km ²	120 m	120 m	120 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	19 km²	2.5 km	2.5 km	2.5 km
	PCW	218 dB	0.07 km ²	150 m	140 m	150 m
Е	LF	219 dB	0.04 km ²	120 m	120 m	120 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	19 km²	2.6 km	2.4 km	2.5 km
	PCW	218 dB	0.07 km ²	150 m	140 m	150 m
S	LF	219 dB	0.03 km ²	100 m	100 m	100 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	13 km²	2.0 km	2.0 km	2.0 km
	PCW	218 dB	0.04 km ²	120 m	120 m	120 m
HVAC	LF	219 dB	0.04 km ²	120 m	120 m	120 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	19 km²	2.5 km	2.5 km	2.5 km
	PCW	218 dB	0.07 km ²	150 m	140 m	150 m

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Table 30: Summary of the SPL_{peak} Southall et al. (2019) TTS impact ranges for the four modelling locations considering the most likely monopile input parameters.

Southall et al. (2019) – TTS		Most likely – Monopile (4,000 kJ) / Impulsive criteria				
Unweig	hted SPL	peak	Area	Maximum range	Minimum range	Mean range
NW	LF	213 dB	0.42 km ²	370 m	370 m	370 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	110 km²	6.0 km	5.7 km	5.8 km
	PCW	212 dB	0.61 km²	440 m	440 m	440 m
Е	LF	213 dB	0.42 km ²	370 m	370 m	370 m
	HF	224 dB	< 0.01 km²	50 m	50 m	50 m
	VHF	196 dB	110 km²	6.3 km	5.5 km	5.8 km
	PCW	212 dB	0.61 km²	440 m	440 m	440 m
S	LF	213 dB	0.29 km ²	300 m	300 m	300 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	66 km²	4.7 km	4.5 km	4.6 km
	PCW	212 dB	0.41 km²	370 m	360 m	370 m
HVAC	LF	213 dB	0.42 km ²	370 m	370 m	370 m
	HF	224 dB	< 0.01 km²	50 m	50 m	50 m
	VHF	196 dB	100 km²	5.8 km	5.7 km	5.7 km
	PCW	212 dB	0.61 km²	440 m	440 m	440 m

Table 31: Summary of the impulsive SEL_{cum} Southall et al. (2019) PTS impact ranges for the four modelling locations considering the most likely monopile input parameters assuming a fleeing receptor.

Southall et al. (2019) – PTS		Most likely – Monopile (4,000 kJ) / Impulsive criteria				
Weight	ed SEL _{cum}		Area	Maximum range	Minimum range	Mean range
NW	LF	183 dB	31 km²	4.8 km	2.4 km	3.1 km
	HF	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	155 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
E	LF	183 dB	41 km²	7.7 km	780 m	3.1 km
	HF	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	155 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
S	LF	183 dB	0.59 km ²	1.0 km	< 100 m	250 m
	HF	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	155 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
HVAC	LF	183 dB	32 km ²	3.9 km	2.6 km	3.2 km
	HF	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	155 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m

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Table 32: Summary of the impulsive SEL_{cum} Southall et al. (2019) TTS impact ranges for the four modelling locations considering the most likely monopile input parameters assuming a fleeing receptor.

Southall et al. (2019) – TTS		Most likely – Monopile (4,000 kJ) / Impulsive criteria				
Weight	ed SEL _{cum}		Area	Maximum range	Minimum range	Mean range
NW	LF	168 dB	1800 km²	32 km	20 km	24 km
	HF	170 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	140 dB	570 km²	16 km	12 km	13 km
	PCW	170 dB	430 km²	14 km	11 km	12 km
E	LF	168 dB	1500 km²	38 km	15 km	21 km
	HF	170 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	140 dB	560 km²	20 km	10 km	13 km
	PCW	170 dB	430 km²	17 km	8.8 km	12 km
S	LF	168 dB	970 km²	25 km	12 km	17 km
	HF	170 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	140 dB	290 km²	12 km	8.1 km	9.5 km
	PCW	170 dB	200 km ²	9.6 km	6.9 km	8.0 km
HVAC	LF	168 dB	1600 km²	29 km	15 km	22 km
	HF	170 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	140 dB	580 km²	15 km	12 km	14 km
	PCW	170 dB	440 km ²	13 km	11 km	12 km

Table 33: Summary of the non-impulsive SEL_{cum} Southall et al. (2019) PTS impact ranges for the four modelling locations considering the most likely monopile input parameters assuming a fleeing receptor.

Southall et al. (2019) – PTS		Most likely – Monopile (4,000 kJ) / Non-impulsive criteria				
Weight	ed SEL _{cum}		Area	Maximum range	Minimum range	Mean range
NW	LF	199 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	HF	198 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	173 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	201 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
E	LF	199 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	HF	198 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	173 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	201 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
S	LF	199 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	HF	198 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	173 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	201 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
HVAC	LF	199 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	HF	198 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	173 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	201 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m

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Table 34: Summary of the non-impulsive SEL_{cum} Southall et al. (2019) TTS impact ranges for the four modelling locations considering the most likely monopile input parameters assuming a fleeing receptor.

Southall et al. (2019) – TTS		Most likely – Monopile (4,000 kJ) / Non-impulsive criteria				
Weight	ed SEL _{cum}		Area	Maximum range	Minimum range	Mean range
NW	LF	179 dB	210 km²	ll km	7.1 km	8.1 km
	HF	178 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	153 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	181 dB	0.35 km²	470 m	160 m	330 m
Е	LF	179 dB	210 km²	15 km	4.5 km	7.6 km
	HF	178 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	153 dB	0.18 km²	440 m	< 100 m	160 m
	PCW	181 dB	1.1 km²	980 m	< 100 m	410 m
S	LF	179 dB	56 km²	6.3 km	2.4 km	4.0 km
	HF	178 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	153 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	181 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
HVAC	LF	179 dB	210 km²	9.7 km	6.6 km	8.1 km
	HF	178 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	153 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	181 dB	0.16 km²	270 m	190 m	220 m

Table 35: Summary of the SPL_{peak} Southall et al. (2019) PTS impact ranges for the four modelling locations for the initial piling strike considering the most likely monopile input parameters.

Southall et al. (2019) – PTS		Most likely – Monopile, first strike (800 kJ) / Impulsive criteria				
Unweig	hted SPL _P	peak	Area	Maximum range	Minimum range	Mean range
NW	LF	219 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	0.99 km ²	560 m	560 m	560 m
	PCW	218 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
E	LF	219 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	0.98 km ²	560 m	560 m	560 m
	PCW	218 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
S	LF	219 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	0.64 km ²	450 m	450 m	450 m
	PCW	218 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
HVAC	LF	219 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	0.99 km ²	560 m	560 m	560 m
	PCW	218 dB	< 0.01 km ²	< 50 m	< 50 m	< 50 m

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Table 36: Summary of the SPL_{peak} Southall et al. (2019) TTS impact ranges for the four modelling locations for the initial piling strike considering the most likely monopile input parameters.

Southall et al. (2019) – TTS		Most likely – Monopile, first strike (800 kJ) / Impulsive criteria				
Unweighted SPL _{peak}		Area	Maximum range	Minimum range	Mean range	
NW	LF	213 dB	0.02 km ²	70 m	70 m	70 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	8.1 km²	1.6 km	1.6 km	1.6 km
	PCW	212 dB	0.02 km ²	90 m	90 m	90 m
E	LF	213 dB	0.02 km ²	70 m	70 m	70 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	8 km²	1.6 km	1.6 km	1.6 km
	PCW	212 dB	0.02 km ²	90 m	90 m	90 m
S	LF	213 dB	< 0.01 km²	60 m	60 m	60 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	5.1 km²	1.3 km	1.3 km	1.3 km
	PCW	212 dB	0.02 km ²	70 m	70 m	70 m
HVAC	LF	213 dB	0.02 km ²	70 m	70 m	70 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	8.1 km ²	1.6 km	1.6 km	1.6 km
	PCW	212 dB	0.02 km ²	90 m	90 m	90 m

Impact ranges – most likely pin pile

Table 37: Summary of the SPL_{peak} Southall et al. (2019) PTS impact ranges for the four modelling locations considering the most likely pin pile input parameters.

Southall et al. (2019) – PTS		Most Likely — Pin pile (1,750 kJ) / Impulsive criteria				
Unweighted SPL _{peak}		Area	Maximum range	Minimum range	Mean range	
NW	LF	219 dB	< 0.01 km²	60 m	60 m	60 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	5.6 km²	1.3 km	1.3 km	1.3 km
	PCW	218 dB	0.02 km ²	70 m	70 m	70 m
E	LF	219 dB	< 0.01 km²	60 m	60 m	60 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	5.5 km ²	1.3 km	1.3 km	1.3 km
	PCW	218 dB	0.02 km ²	70 m	70 m	70 m
S	LF	219 dB	< 0.01 km²	50 m	50 m	50 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	3.6 km ²	1.1 km	1.1 km	1.1 km
	PCW	218 dB	< 0.01 km²	60 m	60 m	60 m
HVAC	LF	219 dB	< 0.01 km²	60 m	60 m	60 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	5.6 km ²	1.3 km	1.3 km	1.3 km
	PCW	218 dB	0.02 km ²	70 m	70 m	70 m



Table 38: Summary of the SPL_{peak} Southall et al. (2019) TTS impact ranges for the four modelling locations considering the most likely pin pile input parameters.

Southall et al. (2019) – TTS		Most Likely – Pin pile (1,750 kJ) / Impulsive criteria				
Unweighted SPL _{peak}		Area	Maximum range	Minimum range	Mean range	
NW	LF	213 dB	0.1 km²	180 m	180 m	180 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	38 km ²	3.5 km	3.4 km	3.5 km
	PCW	212 dB	0.15 km²	220 m	220 m	220 m
Е	LF	213 dB	0.1 km²	180 m	180 m	180 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	37 km ²	3.6 km	3.3 km	3.5 km
	PCW	212 dB	0.15 km ²	220 m	220 m	220 m
S	LF	213 dB	0.07 km ²	150 m	150 m	150 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	23 km ²	2.8 km	2.7 km	2.7 km
	PCW	212 dB	0.1 km²	180 m	180 m	180 m
HVAC	LF	213 dB	0.1 km²	180 m	180 m	180 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	37km ²	3.5 km	3.4 km	3.4 km
	PCW	212 dB	0.15 km ²	220 m	220 m	220 m

Table 39: Summary of the impulsive SEL_{cum} Southall et al. (2019) PTS impact ranges for the four modelling locations considering the most likely pin pile input parameters assuming a fleeing receptor.

Southall et al. (2019) – PTS		Most Likely — Pin pile (1,750 kJ) / Impulsive criteria				
Weighted SEL _{cum}			Area	Maximum range	Minimum range	Mean range
NW	LF	183 dB	0.43 km ²	1.2 km	< 100 m	240 m
	HF	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	155 dB	31 km²	3.6 km	2.9 km	3.1 km
	PCW	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
E	LF	183 dB	4.8 km ²	3.2 km	< 100 m	780 m
	HF	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	155 dB	36 km²	4.6 km	2.1 km	3.2 km
	PCW	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
S	LF	183 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	HF	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	155 dB	3 km²	1.2 km	760 m	970 m
	PCW	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
HVAC	LF	183 dB	0.21 km²	550 m	< 100 m	180 m
	HF	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	155 dB	30 km ²	3.2 km	3.0 km	3.1 km
	PCW	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m

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Table 40: Summary of the impulsive SEL_{cum} Southall et al. (2019) TTS impact ranges for the four modelling locations considering the most likely pin pile input parameters assuming a fleeing receptor.

Southall et al. (2019) – TTS		Most Likely – Pin pile (1,750 kJ) / Impulsive criteria				
Weighted SEL _{cum}		Area	Maximum range	Minimum range	Mean range	
NW	LF	168 dB	1300 km²	26 km	17 km	20 km
	HF	170 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	140 dB	1500 km²	26 km	20 km	22 km
	PCW	170 dB	180 km²	8.9 km	7.0 km	7.6 km
Е	LF	168 dB	1100 km²	33 km	12 km	18 km
	HF	170 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	140 dB	1300 km²	31 km	16 km	20 km
	PCW	170 dB	190 km²	ll km	5.6 km	7.6 km
S	LF	168 dB	6.3 km ²	2.6 km	120 m	1.2 km
	HF	170 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	140 dB	850 km²	20 km	13 km	16 km
	PCW	170 dB	64 km ²	5.2 km	4.0 km	4.5 km
HVAC	LF	168 dB	1100 km²	24 km	14 km	19 km
	HF	170 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	140 dB	1400 km²	24 km	18 km	21 km
	PCW	170 dB	180 km²	8.1 km	7.4 km	7.6 km

Table 41: Summary of the non-impulsive SEL_{cum} Southall et al. (2019) PTS impact ranges for the four modelling locations considering the most likely pin pile input parameters assuming a fleeing receptor.

Southall et al. (2019) – PTS		Most Likely – Pin pile (1,750 kJ) / Non-impulsive criteria				
Weighted SEL _{cum}			Area	Maximum range	Minimum range	Mean range
NW	LF	199 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	HF	198 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	173 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	201 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
E	LF	199 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	HF	198 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	173 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	201 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
S	LF	199 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	HF	198 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	173 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	201 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
HVAC	LF	199 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	HF	198 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	173 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	PCW	201 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m

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Table 42: Summary of the non-impulsive SEL_{cum} Southall et al. (2019) TTS impact ranges for the four modelling locations considering the most likely pin pile input parameters assuming a fleeing receptor.

Southall et al. (2019) – TTS		Most Likely – Pin pile (1,750 kJ) / Non-impulsive criteria				
Weighted SEL _{cum}		Area	Maximum range	Minimum range	Mean range	
NW	LF	179 dB	73 km²	6.9 km	3.9 km	4.8 km
	HF	178 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	153 dB	83 km ²	5.9 km	4.8 km	5.1 km
	PCW	181 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
E	LF	179 dB	82 km ²	10 km	2.0 km	4.6 km
	HF	178 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	153 dB	91 km²	7.3 km	3.7 km	5.3 km
	PCW	181 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
S	LF	179 dB	630 km²	20 km	9.4 km	14 km
	HF	178 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	153 dB	20 km ²	3.0 km	2.2 km	2.5 km
	PCW	181 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
HVAC	LF	179 dB	74 km ²	5.9 km	4.0 km	4.9 km
	HF	178 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	153 dB	82 km ²	5.4 km	5.0 km	5.1 km
	PCW	181 dB	< 0.01 km ²	< 100 m	< 100 m	< 100 m

Table 43: Summary of the SPL_{peak} Southall et al. (2019) PTS impact ranges for the four modelling locations for the initial piling strike considering the most likely pin pile input parameters.

Southall et al. (2019) – PTS		Most Likely – Pin pile, first strike (350 kJ) / Impulsive criteria				
Unweighted SPL _{peak}		Area	Maximum range	Minimum range	Mean range	
NW	LF	219 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	0.08 km ²	170 m	160 m	170 m
	PCW	218 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
E	LF	219 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	0.08 km ²	170 m	160 m	170 m
	PCW	218 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
S	LF	219 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	0.06 km ²	130 m	130 m	130 m
	PCW	218 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
HVAC	LF	219 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	HF	230 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	202 dB	0.08 km ²	170 m	160 m	170 m
	PCW	218 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m

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Table 44: Summary of the SPL $_{\rm peak}$ Southall et al. (2019) TTS impact ranges for the four modelling
locations for the initial piling strike considering the most likely pin pile input parameters.

Southall et al. (2019) – TTS		Most Likely – Pin pile, first strike (350 kJ) / Impulsive criteria				
Unweighted SPL _{peak}		Area	Maximum range	Minimum range	Mean range	
NW	LF	213 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	0.79 km ²	500 m	500 m	500 m
	PCW	212 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
Е	LF	213 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	0.78 km ²	500 m	500 m	500 m
	PCW	212 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
S	LF	213 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	0.51 km²	410 m	400 m	410 m
	PCW	212 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
HVAC	LF	213 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	HF	224 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m
	VHF	196 dB	0.79 km ²	500 m	500 m	500 m
	PCW	212 dB	< 0.01 km ²	< 50 m	< 50 m	< 50 m

Impact ranges –maximum design multiple pin piles

Table 45: Summary of the impulsive SEL_{cum} Southall et al. (2019) PTS impact ranges for three consecutive piles installed at the NW modelling location considering the maximum design pin pile input parameters assuming a fleeing receptor.

Southall et al. (2019) – PTS		Maximum design – 3x Pin piles (3,000 kJ) / Impulsive criteria				
Weighted SELcum		Area	Maximum range	Minimum range	Mean range	
NW	LF	183 dB	43 km ²	5.8 km	2.9 km	3.7 km
	HF	185 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	155 dB	170 km²	9.1 km	6.7 km	7.3 km
PCW 185 dB		< 0.01 km²	< 100 m	< 100 m	< 100 m	

Table 46: Summary of the impulsive SEL_{cum} Southall et al. (2019) TTS impact ranges for three consecutive piles installed at the NW modelling location considering the maximum design pin pile input parameters assuming a fleeing receptor.

Southall et al. (2019) – TTS		Maximum design – 3x Pin piles (3,000 kJ) / Impulsive criteria				
Weighted SELcum		Area	Maximum range	Minimum range	Mean range	
NW	LF	168 dB	2000 km²	35 km	20 km	25 km
	HF	170 dB	< 0.01 km²	< 100 m	< 100 m	<100 m
	VHF	140 dB	2500 km ²	37 km	24 km	28 km
	PCW 170 dB		500 km²	16 km	12 km	13 km



Table 47: Summary of the non-impulsive SEL_{cum} Southall et al. (2019) PTS impact ranges for three consecutive piles installed at the NW modelling location considering the maximum design pin pile input parameters assuming a fleeing receptor.

Southall et al. (2019) – PTS		Maximum design – 3x Pin piles (3,000 kJ) / Non-impulsive criteria				
Weighted SELcum		Area	Maximum range	Minimum range	Mean range	
NW	LF	199 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	HF	198 dB	< 0.01 km²	< 100 m	< 100 m	<100 m
	VHF	173 dB	< 0.01 km²	< 100 m	< 100 m	<100 m
	PCW	201 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m

Table 48: Summary of the non-impulsive SEL_{cum} Southall et al. (2019) TTS impact ranges for three consecutive piles installed at the NW modelling location considering the maximum design pin pile input parameters assuming a fleeing receptor.

Southall et al. (2019) – TTS		Maximum design – 3x Pin piles (3,000 kJ) / Non-impulsive criteria				
Weighted SEL _{cum}		Area	Maximum range	Minimum range	Mean range	
NW	LF	179 dB	240 km²	12 km	7.6 km	8.8 km
	HF	178 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	VHF	153 dB	300 km²	12 km	8.8 km	9.7 km
	PCW	181 dB	0.67 km ²	750 m	250 m	450 m

Discussion of Marine Mammal Results

- 5.2.2.6 The ranges of impact using the Southall et al. (2019) criteria vary depending on the hearing (species) group and severity of impact. Looking at the monopile results for the maximum design parameters as an example (Table 15 and Table 16), the SEL_{cum} results using the LF weighting lead to the greatest ranges as the HF, VHF and PCW weightings filter out much of the piling energy at lower frequencies. It is also worth noting that the greatest ranges are calculated for the transects travelling through the deepest water and the number of transects on this trajectory are somewhat limited; therefore only a small proportion of the site is subject to these noise levels. This is clearly shown in Section 5.1.
- 5.2.2.7 The SEL_{cum} results show that larger ranges are expected for pin piles than for monopiles for HF and VHF hearing groups. This is due to the differences between the marine mammal hearing group weightings and the sound frequencies produced by the different size piles.
- 5.2.2.8 The frequency spectra used as inputs to the model (Figure 5) show that the noise from pin piles contains more high frequency components than the noise from monopiles. The overall unweighted noise level is higher for the monopile due to the low frequency components of piling noise (i.e. most of the pile strike energy is in the lower frequencies <250 Hz). The HF and VHF cetacean filters (Table 1) both remove much of the low frequency components of the noise, as the species in these groups are much less sensitive to noise at these frequencies. This leaves the higher frequency noise, which in the case of pin piles is higher than that for the monopiles.
- 5.2.2.9 To illustrate this, **Figure 16** and **Figure 17** show the sound frequency spectra for monopiles and pin piles, adjusted (weighted) to account for the sensitivities of the different cetacean hearing groups. These can be compared to the original unweighted frequency spectra in

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Figure 5 (shown faintly in **Figure 16** and **Figure 17**). For the HF and VHF cetacean groups, higher levels are present in the weighted pin pile spectrum compared to the monopile.

Figure 16: Filtered noise inputs for monopiles using the Southall et al. (2019) weightings. The lighter coloured bars show the unweighted one-third octave levels.



Figure 17: Filtered noise inputs for pin piles using the Southall et al. (2019) weightings. The lighter coloured bars show the unweighted one-third octave levels.

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5.2.3 Fish criteria

- 5.2.3.1 **Table 49** to **Table 64** give detailed summaries of the impact ranges for species of fish based on the injury criteria found in the Popper et al. (2014) guidance. Interpretation of these modelling results are provided in **Volume A2**, **Chapter 3**: **Fish and Shellfish Ecology**. As discussed in **Section 2.2.2**, the Popper et al. (2014) criteria are given as unweighted SPL_{peak} and unweighted SEL_{cum}, grouping fish by physiology with respect to swim bladder. The Popper et al. (2014) criteria for impact piling are given in **Table 4**. In addition, instantaneous SPL_{peak} values for the first strike of each scenario have also been given. A sequential piling scenario of three pin piles installed at the NW location in a 24-hour period has also been considered and results for this are presented in **Table 65** and **Table 66**. Considering a fleeing animal, the addition of the extra piling scenarios does not have a great effect on impact ranges, but larger ranges are predicted for a stationary animal as they are essentially receiving exposure from three times as many pile strikes in a 24-hour period.
- 5.2.3.2 As discussed in **paragraphs 2.2.2.2** to **2.2.2.4** for SEL_{cum} criteria, both fleeing animal and stationary animal models have been used. For the fleeing animal model, a speed of 1.5 ms⁻¹ has been assumed (Hirata, 1999).
- 5.2.3.3 It should be noted that some of the same noise levels are used as criteria for multiple effects. This is as per the Popper et al. (2014) guidelines (Table 4), which is based on a comprehensive literature review. The data available to create the criteria are very limited for fish and most criteria in Table 4 are "greater than", with a specific threshold not identified. All ranges associated with criteria defined with a ">" are therefore conservative and in practice the actual range at which an effect could occur will be somewhat lower.
- 5.2.3.4 The results show that the largest impact ranges occur in the deeper water areas, with maximum SPL_{peak} recoverable injury ranges of up to 1.3 km and maximum predicted SEL_{cum} TTS ranges of 26 km assuming a fleeing receptor and 38 km assuming a stationary receptor. Other injury criteria from Popper et al. (2014) result in much smaller ranges.

Impact ranges – maximum design monopile

Table 49: Summary of the unweighted SPL_{peak} impact ranges for the various impact piling criteria for fish from Popper et al. (2014) considering the maximum design monopile input parameters.

Popper et al. (2014)		Maximum design — Monopile (5,000 kJ)					
Unweig	hted SPL _{peak}	Area	Maximum range	Minimum range	Mean range		
NW	213 dB	0.57 km ²	430 m	430 m	430 m		
	207 dB	4.9 km ²	1.3 km	1.2 km	1.2 km		
E	213 dB	0.57 km ²	430 m	430 m	430 m		
	207 dB	4.8 km ²	1.2 km	1.2 km	1.2 km		
S	213 dB	0.39 km ²	360 m	350 m	350 m		
	207 dB	3.3 km ²	1.0 km	1.0 km	1.0 km		
HVAC	213 dB	0.57 km ²	430 m	430 m	430 m		
	207 dB	4.9 km ²	1.2 km	1.2 km	1.2 km		

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Table 50: Summary of the unweighted SEL_{cum} impact ranges for the various impact piling criteria for fish from Popper et al. (2014) considering the maximum design monopile input parameters assuming a fleeing receptor.

Popper et al. (2014)		Maximum design — Monopile (5,000 kJ) / Fleeing receptor			
Unweighted SEL _{cum}		Area	Maximum range	Minimum range	Mean range
NW	219 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	216 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	210 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	207 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	203 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	186 dB	890 km²	21 km	15 km	17 km
E	219 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	216 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	210 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	207 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	203 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	186 dB	830 km ²	26 km	12 km	16 km
S	219 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	216 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	210 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	207 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	203 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	186 dB	470 km ²	15 km	9.5 km	12 km
HVAC	219 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	216 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	210 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	207 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	203 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	186 dB	860 km ²	19 km	14 km	17 km

Table 51: Summary of the unweighted SEL_{cum} impact ranges for the various impact piling criteria for fish from Popper et al. (2014) considering the maximum design monopile input parameters assuming a stationary receptor.

Popper et al. (2014)		Maximum design — Monopile (5,000 kJ) / Stationary receptor				
Unweig	hted SEL _{cum}	Area	Maximum range	Minimum range	Mean range	
NW	219 dB	1.8 km²	760 m	740 m	750 m	
	216 dB	5.0 km ²	1.3 km	1.3 km	1.3 km	
	210 dB	34 km ²	3.4 km	3.3 km	3.3 km	
	207 dB	80 km²	5.1 km	4.9 km	5.1 km	
	203 dB	210 km²	8.4 km	7.9 km	8.2 km	
	186 dB	2500 km ²	33 km	26 km	28 km	
E	219 dB	1.7 km²	750 m	740 m	750 m	
	216 dB	5.0 km ²	1.3 km	1.3 km	1.3 km	
	210 dB	34 km ²	3.5 km	3.2 km	3.3 km	
	207 dB	79 km ²	5.4 km	4.8 km	5.0 km	

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Popper et al. (2014)		Maximum design — Monopile (5,000 kJ) / Stationary receptor				
Unweig	hted SEL _{cum}	Area	Maximum range	Minimum range	Mean range	
	203 dB	210 km ²	9.1 km	7.4 km	8.2 km	
	186 dB	2400 km ²	38 km	23 km	27 km	
S	219 dB	1.2 km ²	630 m	620 m	630 m	
	216 dB	3.4 km ²	1.1 km	1.0 km	1.0 km	
	210 dB	22 km ²	2.7 km	2.6 km	2.7 km	
	207 dB	50 km²	4.0 km	4.0 km	4.0 km	
	203 dB	130 km²	6.6 km	6.3 km	6.4 km	
	186 dB	1700 km²	28 km	20 km	23 km	
HVAC	219 dB	1.8 km²	760 m	750 m	760 m	
	216 dB	5.0 km ²	1.3 km	1.3 km	1.3 km	
	210 dB	34 km ²	3.3 km	3.3 km	3.3 km	
	207 dB	77 km²	5.0 km	5.0 km	5.0 km	
	203 dB	200 km ²	8.1 km	8.0 km	8.0 km	
	186 dB	2500 km²	31 km	25 km	28 km	

Table 52: Summary of the unweighted SPL_{peak} impact ranges for the various impact piling criteria for fish from Popper et al. (2014) for the initial piling strike considering the maximum design monopile input parameters.

Popper et al. (2014)		Maximum design – Monopile, first strike (1,000 kJ)				
Unweig	hted SPL _{peak}	Area	Maximum range	Minimum range	Mean range	
NW	213 dB	0.03 km ²	100 m	100 m	100 m	
	207 dB	0.27 km ²	300 m	300 m	300 m	
Е	213 dB	0.03 km²	100 m	100 m	100 m	
	207 dB	0.27 km ²	300 m	300 m	300 m	
S	213 dB	0.02 km ²	80 m	80 m	80 m	
	207 dB	0.18 km²	240 m	240 m	240 m	
HVAC	213 dB	0.03 km ²	100 m	100 m	100 m	
	207 dB	0.27 km ²	300 m	300 m	300 m	

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Impact ranges – maximum design pin pile

Table 53: Summary of the unweighted SPL_{peak} impact ranges for the various impact piling criteria for fish from Popper et al. (2014) considering the maximum design pin pile input parameters.

Popper et al. (2014)		Maximum design — Pin pile (3,000 kJ)				
Unweig	hted SPL _{peak}	Area	Maximum range	Minimum range	Mean range	
NW	213 dB	0.27 km ²	300 m	300 m	300 m	
	207 dB	2.4 km ²	890 m	880 m	880 m	
E	213 dB	0.27 km ²	300 m	290 m	300 m	
	207 dB	2.4 km ²	880 m	880 m	880 m	
S	213 dB	0.18 km²	240 m	240 m	240 m	
	207 dB	1.6 km²	720 m	720 m	720 m	
HVAC	213 dB	0.27 km ²	300 m	300 m	300 m	
	207 dB	2.4 km ²	880 m	880 m	880 m	

Table 54: Summary of the unweighted SEL_{cum} impact ranges for the various impact piling criteria for fish from Popper et al. (2014) considering the maximum design pin pile input parameters assuming a fleeing receptor.

Popper et al. (2014)		Maximum design — Pin pile (3,000 kJ) / Fleeing receptor				
Unweighted SEL _{cum}		Area	Maximum range	Minimum range	Mean range	
NW	219 dB	< 0.01 km ²	< 100 m	< 100 m	< 100 m	
	216 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	210 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	207 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	203 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	186 dB	620 km ²	17 km	13 km	14 km	
E	219 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	216 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	210 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	207 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	203 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	186 dB	590 km²	22 km	10 km	13 km	
S	219 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	216 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	210 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	207 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	203 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	186 dB	300 km ²	12 km	7.8 km	9.7 km	
HVAC	219 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	216 dB	< 0.01 km ²	< 100 m	< 100 m	< 100 m	
	210 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	207 dB	< 0.01 km ²	< 100 m	< 100 m	< 100 m	
	203 dB	< 0.01 km ²	< 100 m	< 100 m	< 100 m	
	186 dB	610 km²	16 km	12 km	14 km	

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Table 55: Summary of the unweighted SEL_{cum} impact ranges for the various impact piling criteria for fish from Popper et al. (2014) considering the maximum design pin pile input parameters assuming a stationary receptor.

Popper et al. (2014)		Maximum design — Pin pile (3,000 kJ) / Stationary receptor				
Unweighted SEL _{cum}		Area	Maximum range	Minimum range	Mean range	
NW	219 dB	0.86 km ²	530 m	520 m	530 m	
	216 dB	2.5 km ²	910 m	890 m	900 m	
	210 dB	19 km²	2.5 km	2.4 km	2.4 km	
	207 dB	46 km ²	3.9 km	3.8 km	3.8 km	
	203 dB	130 km²	6.7 km	6.3 km	6.5 km	
	186 dB	2000 km ²	29 km	24 km	26 km	
E	219 dB	0.86 km²	530 m	520 m	530 m	
	216 dB	2.5 km ²	900 m	890 m	900 m	
	210 dB	18 km²	2.5 km	2.4 km	2.4 km	
	207 dB	46 km ²	4.0 km	3.7 km	3.8 km	
	203 dB	130 km²	7.1 km	6.0 km	6.5 km	
	186 dB	1900 km²	34 km	21 km	25 km	
S	219 dB	0.59 km ²	440 m	430 m	440 m	
	216 dB	1.7 km²	740 m	730 m	740 m	
	210 dB	12 km²	2.0 km	2.0 km	2.0 km	
	207 dB	29 km ²	3.1 km	3.0 km	3.0 km	
	203 dB	81 km²	5.2 km	5.0 km	5.1 km	
	186 dB	1400 km²	25 km	18 km	21 km	
HVAC	219 dB	0.86 km²	530 m	520 m	530 m	
	216 dB	2.5 km ²	900 m	890 m	900 m	
	210 dB	19 km²	2.4 km	2.4 km	2.4 km	
	207 dB	45 km ²	3.8 km	3.8 km	3.8 km	
	203 dB	130 km²	6.4 km	6.4 km	6.4 km	
	186 dB	2000 km ²	28 km	23 km	25 km	

Table 56: Summary of the unweighted SPL_{peak} impact ranges for the various impact piling criteria for fish from Popper et al. (2014) for the initial piling strike considering the maximum design pin pile input parameters.

Popper et al. (2014)		Maximum design – Pin pile, first strike (600 kJ)				
Unweig	hted SPL _{peak}	Area	Maximum range	Minimum range	Mean range	
NW	213 dB	< 0.01 km ²	< 50 m	< 50 m	< 50 m	
	207 dB	0.07 km ²	150 m	150 m	150 m	
E	213 dB	< 0.01 km ²	50 m	50 m	50 m	
	207 dB	0.07 km ²	150 m	150 m	150 m	
S	213 dB	< 0.01 km ²	< 50 m	< 50 m	< 50 m	
	207 dB	0.05 km ²	120 m	120 m	120 m	
HVAC	213 dB	< 0.01 km ²	50 m	50 m	50 m	
	207 dB	0.07 km ²	150 m	150 m	150 m	

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Impact ranges – most likely monopile

Table 57: Summary of the unweighted SPL_{peak} impact ranges for the various impact piling criteria for fish from Popper et al. (2014) considering the most likely monopile input parameters.

Popper et al. (2014)		Most likely – Monopile (4,000 kJ)				
Unweig	hted SPL _{peak}	Area	Maximum range	Minimum range	Mean range	
NW	213 dB	0.42 km ²	370 m	370 m	370 m	
	207 dB	3.7 km ²	1.1 km	1.1 km	1.1 km	
E	213 dB	0.42 km ²	370 m	370 m	370 m	
	207 dB	3.6 km ²	1.1 km	1.1 km	1.1 km	
S	213 dB	0.29 km ²	300 m	300 m	300 m	
	207 dB	2.5 km ²	890 m	890 m	890 m	
HVAC	213 dB	0.42 km ²	370 m	370 m	370 m	
	207 dB	3.7 km ²	1.1 km	1.1 km	1.1 km	

Table 58: Summary of the unweighted SEL_{cum} impact ranges for the various impact piling criteria for fish from Popper et al. (2014) considering the most likely monopile input parameters assuming a fleeing receptor.

Popper et al. (2014) Most likely – Monopile (4,000 kJ) / Fleeing receptor					
Unweig	hted SEL _{cum}	Area	Maximum range	Minimum range	Mean range
NW	219 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	216 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	210 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	207 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	203 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	186 dB	590 km²	16 km	13 km	14 km
Е	219 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	216 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	210 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	207 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	203 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	186 dB	580 km²	20 km	10 km	13 km
S	219 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	216 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	210 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	207 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	203 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	186 dB	300 km²	12 km	8.2 km	9.7 km
HVAC	219 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	216 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	210 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	207 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	203 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m
	186 dB	600 km ²	15 km	13 km	14 km

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Table 59: Summary of the unweighted SEL_{cum} impact ranges for the various impact piling criteria for fish from Popper et al. (2014) considering the most likely monopile input parameters assuming a stationary receptor.

Popper et al. (2014) Most likely – Monopile (4,000 kJ) / Stationary receptor					
Unweig	ihted SEL _{cum}	Area	Maximum range	Minimum range	Mean range
NW	219 dB	0.27 km ²	300 m	290 m	300 m
	216 dB	0.8 km ²	520 m	500 m	510 m
	210 dB	6.6 km ²	1.5 km	1.5 km	1.5 km
	207 dB	18 km²	2.4 km	2.4 km	2.4 km
	203 dB	58 km²	4.4 km	4.2 km	4.3 km
	186 dB	1400 km²	24 km	20 km	21 km
E	219 dB	0.27 km ²	300 m	290 m	300 m
	216 dB	0.8 km ²	510 m	500 m	510 m
	210 dB	6.5 km ²	1.5 km	1.4 km	1.4 km
	207 dB	17 km²	2.4 km	2.3 km	2.4 km
	203 dB	58 km²	4.6 km	4.1 km	4.3 km
	186 dB	1400 km²	28 km	18 km	21 km
S	219 dB	0.19 km²	250 m	240 m	250 m
	216 dB	0.56 km²	430 m	420 m	430 m
	210 dB	4.4 km ²	1.2 km	1.2 km	1.2 km
	207 dB	ll km²	1.9 km	1.9 km	1.9 km
	203 dB	36 km²	3.4 km	3.4 km	3.4 km
	186 dB	920 km²	19 km	16 km	17 km
HVAC	219 dB	0.27 km ²	300 m	290 m	300 m
	216 dB	0.8 km ²	510 m	500 m	510 m
	210 dB	6.6 km ²	1.5 km	1.5 km	1.5 km
	207 dB	17 km²	2.4 km	2.4 km	2.4 km
	203 dB	57 km²	4.3 km	4.3 km	4.3 km
	186 dB	1400 km ²	23 km	20 km	21 km

Table 60: Summary of the unweighted SPL_{peak} impact ranges for the various impact piling criteria for fish from Popper et al. (2014) for the initial piling strike considering the most likely monopile input parameters.

Popper et al. (2014)		Most likely – Monopile, first strike (800 kJ)				
Unweig	hted SPL _{peak}	Area	Maximum range	Minimum range	Mean range	
NW	213 dB	0.02 km ²	70 m	70 m	70 m	
	207 dB	0.15 km ²	220 m	220 m	220 m	
E	213 dB	0.02 km ²	70 m	70 m	70 m	
	207 dB	0.15 km²	220 m	220 m	220 m	
S	213 dB	< 0.01 km²	60 m	60 m	60 m	
	207 dB	0.1 km²	180 m	180 m	180 m	
HVAC	213 dB	0.02 km ²	70 m	70 m	70 m	
	207 dB	0.16 km ²	220 m	220 m	220 m	



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Impact ranges – most likely pin pile

Table 61: Summary of the unweighted SPL_{peak} impact ranges for the various impact piling criteria for fish from Popper et al. (2014) considering the most likely pin pile input parameters.

Popper et al. (2014)		Most likely – Pin Pile (1,750 kJ)					
Unweig	hted SPL _{peak}	Area	Maximum range	Minimum range	Mean range		
NW	213 dB	0.1 km²	180 m	180 m	180 m		
	207 dB	0.95 km²	550 m	550 m	550 m		
E	213 dB	0.1 km²	180 m	180 m	180 m		
	207 dB	0.94 km²	550 m	550 m	550 m		
S	213 dB	0.07 km ² 150 m 1		150 m	105 m		
	207 dB	0.62 km ²	450 m	450 m	450 m		
HVAC	213 dB	0.1 km²	180 m	180 m	180 m		
	207 dB	0.95 km²	550 m	550 m	550 m		

Table 62: Summary of the unweighted SEL_{cum} impact ranges for the various impact piling criteria for fish from Popper et al. (2014) considering the most likely pin pile input parameters assuming a fleeing receptor.

Popper	et al. (2014)	Most likely – Pin Pile (1,750 kJ) / Fleeing receptor				
Unweig	Unweighted SEL _{cum} Area Maximum range Minimum range M				Mean range	
NW	219 dB	< 0.01 km ²	< 100 m	< 100 m	< 100 m	
	216 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	210 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	207 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	203 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	186 dB	250 km ²	ll km	8.2 km	9.0 km	
Е	219 dB	< 0.01 km ²	< 100 m	< 100 m	< 100 m	
	216 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	210 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	207 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	203 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	186 dB	260 km ²	13 km	6.7 km	8.9 km	
S	219 dB	< 0.01 km ²	< 100 m	< 100 m	< 100 m	
	216 dB	< 0.01 km ²	< 100 m	< 100 m	< 100 m	
	210 dB	< 0.01 km ²	< 100 m	< 100 m	< 100 m	
	207 dB	< 0.01 km ²	< 100 m	< 100 m	< 100 m	
	203 dB	< 0.01 km ²	< 100 m	< 100 m	< 100 m	
	186 dB	100 km²	6.6 km	5.0 km	5.6 km	
HVAC	219 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	216 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	210 dB	< 0.01 km ²	< 100 m	< 100 m	< 100 m	
	207 dB	< 0.01 km ²	< 100 m	< 100 m	< 100 m	
	203 dB	< 0.01 km ²	< 100 m	< 100 m	< 100 m	
	186 dB	260 km ²	9.6 km	8.7 km	9.1 km	

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Table 63: Summary of the unweighted SEL_{cum} impact ranges for the various impact piling criteria for fish from Popper et al. (2014) considering the most likely pin pile input parameters assuming a stationary receptor.

Popper	et al. (2014)) Most likely – Pin Pile (1,750 kJ) / Stationary receptor			
Unweighted SEL _{cum}		Area	Maximum range	Minimum range	Mean range
NW	219 dB	0.07 km ²	150 m	140 m	150 m
	216 dB	0.2 km ²	260 m	250 m	260 m
	210 dB	1.8 km²	760 m	740 m	750 m
	207 dB	5.0 km²	1.3 km	1.3 km	1.3 km
	203 dB	19 km²	2.5 km	2.4 km	2.4 km
	186 dB	850 km²	18 km	16 km	16 km
E	219 dB	0.07 km²	150 m	140 m	150 m
	216 dB	0.2 km ²	260 m	250 m	260 m
	210 dB	1.7 km²	750 m	740 m	750 m
	207 dB	5 km²	1.3 km	1.3 km	1.3 km
	203 dB	18 km²	2.5 km	2.4 km	2.4 km
	186 dB	850 km²	21 km	14 km	16 km
S	219 dB	0.05 km²	130 m	120 m	130 m
	216 dB	0.13 km²	210 m	200 m	210 m
	210 dB	1.1 km²	610 m	600 m	610 m
	207 dB	3.3 km ²	1.0 km	1.0 km	1.0 km
	203 dB	12 km²	2.0 km	1.9 km	1.9 km
	186 dB	530 km²	14 km	12 km	13 km
HVAC	219 dB	0.07 km ²	150 m	140 m	150 m
	216 dB	0.2 km ²	260 m	250 m	260 m
	210 dB	1.8 km²	760 m	750 m	760 m
	207 dB	5 km²	1.3 km	1.3 km	1.3 km
	203 dB	19 km²	2.5 km	2.5 km	2.5 km
	186 dB	860 km ²	17 km	16 km	17 km

Table 64: Summary of the unweighted SPL_{peak} impact ranges for the various impact piling criteria for fish from Popper et al. (2014) for the initial piling strike considering the most likely pin pile input parameters.

Popper et al. (2014)		Most likely – Pin pile, first strike (350 kJ)				
Unweig	ihted SPL _{peak}	Area	Maximum range	Minimum range	Mean range	
NW	213 dB	< 0.01 km²	< 50 m	< 50 m	< 50 m	
	207 dB	< 0.01 km ²	70 m	60 m	70 m	
Е	213 dB	< 0.01 km ²	< 50 m	< 50 m	< 50 m	
	207 dB	< 0.01 km²	70 m	60 m	70 m	
S	213 dB	< 0.01 km ²	< 50 m	< 50 m	< 50 m	
	207 dB	< 0.01 km ²	50 m	50 m	50 m	
HVAC	213 dB	< 0.01 km ²	< 50 m	< 50 m	< 50 m	
	207 dB	< 0.01 km ²	70 m	60 m	70 m	



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Impact ranges – maximum design, multiple pin piles

Table 65: Summary of the unweighted SEL_{cum} impact ranges for the various impact piling criteria for fish from Popper et al. (2014) considering the maximum design pin pile input parameters assuming a fleeing receptor.

Popper et al. (2014)		Maximum design — Pin Pile (3,000 kJ) / Fleeing receptor				
Unweighted SEL _{cum}		Area	Area Maximum range Minimum range		Mean range	
NW	219 dB	< 0.01 km²	< 100 m	< 100 m	<100 m	
216 dB 210 dB	216 dB	< 0.01 km²	< 100 m	< 100 m	<100 m	
	210 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	207 dB	< 0.01 km²	< 100 m	< 100 m	< 100 m	
	203 dB	< 0.01 km²	< 100 m	< 100 m	<100 m	
	186 dB	640 km²	18 km	13 km	14 km	

Table 66: Summary of the unweighted SEL_{cum} impact ranges for the various impact piling criteria for fish from Popper et al. (2014) considering the maximum design pin pile input parameters assuming a stationary receptor.

Popper et al. (2014)		Maximum design — Pin Pile (3,000 kJ) / Stationary receptor					
Unweighted SEL _{cum}		Area	Maximum range	Minimum range	Mean range		
NW	219 dB	5.1 km²	1.3 km	1.3 km	1.3 km		
	216 dB	13 km²	2.1 km	2.0 km	2.1 km		
210 dB		77 km²	5.0 km	4.9 km	4.9 km		
207 c 203 c	207 dB	160 km²	7.3 km	7.0 km	7.2 km		
	203 dB	370 km²	11 km	11 km	11 km		
	186 dB	3300 km ²	38 km	30 km	33 km		

5.3 Simultaneous piling at two locations

5.3.1 Introduction

- 5.3.1.1 Additional modelling has been carried out to investigate the potential impacts of two piling installations occurring simultaneously at separated foundation locations. Using the MDS monopile and pin pile scenarios from Section 4.3.2, modelling has been carried out for piling simultaneously at both the NW and E modelling locations, representing a worst-case spatial spread of locations. All modelling in this section assumes that the two piling operations start at the same time.
- 5.3.1.2 When considering SEL_{cum} modelling, piling from multiple sources has the ability to increase impact ranges and areas significantly as, in this case, it introduces double the number of pile strikes to the water. Unlike the sequential piling investigated in the previous sections, the fleeing receptor can be closer to the source for more pile strikes, resulting in higher received noise levels. Figure 18 shows the TTS contour for fish from Popper et al. (2014) given as unweighted SEL_{cum} for a fleeing receptor. The blue contours show the impact from each modelling location individually (as presented in the previous section), and the red contour shows the increase in impact when both sources occur simultaneously, resulting in a contour encircling the previous two.





5.3.1.3 This modelling scenario was chosen to provide the greatest geographical spread of impact range contours. In a modelling scenario where two piles are installed adjacent to one another, there would be an expansion of the contour in all directions, but smaller than on the NW-E spread extent seen in **Figure 18**. It is understood that for operational safety reasons, the course or route of piling rigs would be designed to ensure that they would not be positioned near to each other at any time during piling, so the immediately adjacent scenario should not occur. Thus the 'separated' scenario here represents a worst case.







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5.3.1.4 Section 5.3.2 and Section 5.3.3 present contour plots for the multiple location piling scenarios alongside tables showing the increases in overall area. Impact ranges have not been presented in this section as there are two starting points for receptors. Fields denoted with a dash "-" show where there is no cumulative effect when the two piles are installed simultaneously, generally where the individual ranges are small enough that the distant site does not produce an influencing additional exposure. Contours that are too small to be seen clearly at the scale of the figures have not been included.

5.3.2 Marine mammal criteria

5.3.2.1 **Table 67** to **Table 70** show a summary of the marine mammal PTS and TTS impact areas for impact piling at the NW and E locations simultaneously, showing the areas for impact piling at the individual locations as well as the in-combination area. These results are also illustrated in Figure 19 to Figure 22.

Table 67: Summary of the impact areas for the installation of monopile foundations using the maximum design parameters at the NW and E modelling locations for marine mammals using the impulsive Southall et al. (2019) SEL_{cum} criteria assuming a fleeing receptor.

Southall et al. (2019)			Maximum design – Monopile (5,000 kJ) / Impulsive criteria			
Weighted SEL _{cum}			NW area	E area	In-combination area	
PTS	LF	183 dB	66 km²	76 km²	1000 km²	
	HF	185 dB	< 0.01 km²	< 0.01 km²	-	
	VHF	155 dB	< 0.01 km²	0.09 km ²	-	
	PCW	185 dB	< 0.01 km²	< 0.01 km²	-	
TTS	LF	168 dB	2200 km ²	1800 km²	4500 km ²	
	HF	170 dB	< 0.01 km²	< 0.01 km ²	-	
	VHF	140 dB	860 km ²	810 km²	2400 km ²	
	PCW	170 dB	670 km ²	640 km ²	2100 km ²	

Table 68: Summary of the impact areas for the installation of monopile foundations using the maximum design parameters at the NW and E modelling locations for marine mammals using the non-impulsive Southall et al. (2019) SEL_{cum} criteria assuming a fleeing receptor.

Southall et al. (2019)			Maximum design – Monopile (5,000 kJ) / Non-impulsive criteria			
Weighted SEL _{cum}			NW area	E area	In-combination area	
PTS	LF	199 dB	< 0.01 km²	< 0.01 km ²	-	
	HF	198 dB	< 0.01 km²	< 0.01 km²	-	
	VHF	173 dB	< 0.01 km²	< 0.01 km ²	-	
	PCW	201 dB	< 0.01 km²	< 0.01 km²	-	
TTS	LF	179 dB	300 km ²	290 km ²	1600 km²	
	HF	178 dB	< 0.01 km²	< 0.01 km ²	-	
	VHF	153 dB	5.3 km ²	7.7 km ²	-	
	PCW	181 dB	11 km²	14 km²	370 km ²	

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Table 69: Summary of the impact areas for the installation of pin pile foundations using the maximum design parameters at the NW and E modelling locations for marine mammals using the impulsive Southall et al. (2019) SEL_{cum} criteria assuming a fleeing receptor.

Southall et al. (2019)			Maximum design – Pin pile (3,000 kJ) / Impulsive criteria			
Weighted S			NW area	E area	In-combination area	
PTS	LF	183 dB	42 km ²	53 km²	920 km ²	
	HF	185 dB	< 0.01 km²	< 0.01 km ²	-	
	VHF	155 dB	160 km²	170 km²	1100 km²	
	PCW	185 dB	< 0.01 km²	< 0.01 km²	-	
TTS	LF	168 dB	2000 km ²	1600 km²	4200 km ²	
	HF	170 dB	< 0.01 km²	< 0.01 km ²	-	
	VHF	140 dB	2500 km²	2100 km²	4700 km ²	
	PCW	170 dB	480 km ²	470 km ²	1700 km²	

Table 70: Summary of the impact areas for the installation of pin pile foundations using the maximum design parameters at the NW and E modelling locations for marine mammals using the non-impulsive Southall et al. (2019) SEL_{cum} criteria assuming a fleeing receptor.

Southall et al. (2019)			Maximum design – Pin pile (3,000 kJ) / Non-impulsive criteria			
Weighted S			NW area	E area	In-combination area	
PTS	LF	199 dB	< 0.01 km²	< 0.01 km²	-	
	HF	198 dB	< 0.01 km²	< 0.01 km²	-	
	VHF	173 dB	< 0.01 km²	< 0.01 km²	-	
	PCW	201 dB	< 0.01 km²	< 0.01 km²	-	
TTS	LF	179 dB	240 km ²	240 km ²	1500 km²	
	HF	178 dB	< 0.01 km²	< 0.01 km²	-	
	VHF	153 dB	290 km ²	290 km ²	1400 km²	
	PCW	181 dB	0.44 km ²	1.7 km²	-	







































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5.3.3 Fish criteria

5.3.3.1 The impact areas for fish, using the Popper et al. (2014) criteria, showing the results for impact piling at the NW and E locations, as well as the in-combination area for simultaneous piling are summarised in Table 71 and Table 72. These results are shown as contour plots in Figure 23 and Figure 24.

Table 71: Summary of the impact areas for the installation of monopile foundations using the maximum design parameters at the NW and E modelling locations for fish using the Popper et al. (2014) SEL_{cum} criteria for impact piling assuming both a fleeing and stationary receptor.

Popper et al. (2014)		Maximum design – Monopile (5,000 kJ)				
Weighted SEL _{cum}		NW area	E area	In-combination area		
Fleeing	219 dB	< 0.01 km²	< 0.01 km²	-		
	216 dB	< 0.01 km²	< 0.01 km²	-		
	210 dB	< 0.01 km²	< 0.01 km²	-		
	207 dB	< 0.01 km²	< 0.01 km²	-		
	203 dB	< 0.01 km²	< 0.01 km²	-		
	186 dB	890 km ²	830 km ²	2500 km²		
Stationary	219 dB	1.8 km²	1.7 km²	-		
	216 dB	5.0 km ²	5.0 km ²	-		
	210 dB	34 km²	34 km²	-		
	207 dB	80 km²	79 km²	-		
	203 dB	210 km ²	210 km ²	-		
	186 dB	2500 km ²	2400 km ²	4500 km ²		

Table 72: Summary of the impact areas for the installation of monopile foundations using the maximum design parameters at the NW and E modelling locations for fish using the Popper et al. (2014) SEL_{cum} criteria for impact piling assuming both a fleeing and stationary receptor.

Popper et al. (2014) Weighted SEL _{cum}		Maximum design — Pin pile (3,000 kJ)			
		NW area	E area	In-combination area	
Fleeing	219 dB	< 0.01 km²	< 0.01 km ²	-	
	216 dB	< 0.01 km ²	< 0.01 km ²	-	
	210 dB	< 0.01 km ²	< 0.01 km ²	-	
	207 dB	< 0.01 km ²	< 0.01 km ²	-	
	203 dB	< 0.01 km ²	< 0.01 km ²	-	
	186 dB	620 km ²	590 km ²	2000 km ²	
Stationary	219 dB	0.86 km ²	0.86 km ²	-	
	216 dB	2.5 km ²	2.5 km ²	-	
	210 dB	19 km²	18 km²	-	
	207 dB	46 km²	46 km²	-	
	203 dB	130 km²	130 km ²	-	
	186 dB	2000 km ²	1900 km²	3800 km ²	





Hornsea Four

Figure 23 Contour plots showing the cumulative impacts of simultaneous installation of monopile foundations at the NW and E modelling locations for fish using the Popper et al. (2014) impact piling criteria assuming fleeing and stationary receptors

🔲 Array Area
Modelling Locations
Noise Level (dB)
186
203
207
210
216
Water Depth (m below CD)
95



Coordinate system: ETRS 1989 UTM Zone 31N Scale@A3: 1:600,000 10 20 Kilometres 0

10 Nautical Miles 0 5

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Figure 23 Multiple Piles Document no: HOW04GB0269 Created by: BPHB Checked by: AL Approved by: LK







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6 Other Noise Sources

6.1 Introduction

- 6.1.1.1 Although impact piling is expected to be the primary noise source for consideration during offshore wind farm construction and development (Bailey et al. 2014), several other anthropogenic noise sources may be present. Each of these has been considered, and relevant biological noise criteria presented, in this section.
- 6.1.1.2 **Table 73** provides a summary of the various noise producing sources, aside from impact piling, that are expected to be present during the construction and operation of Hornsea Four.

Table 73: Summary of the possible noise making activities at Hornsea Four other than impact piling.

Activity	Description
Dredging	Trailer suction hopper dredger may be required on site for the export cable, array cable and interconnector cable installation, as well as seabed preparation works for certain foundation
	options.
Drilling	Necessary in case of impact piling refusal.
Cable laying	Noise from the cable laying vessel and any other associated noise during the offshore cable
	installation.
Rock	Potentially required on site for installation of offshore cables (cable crossings and cable protection)
placement	and scour protection around foundation structures.
Trenching	Plough trenching may be required during offshore cable installation.
Vessel noise	Jack-up barges for piling substructure and WTG installation. Other large and medium sized vessels
	on site to carry out other construction tasks, and anchor handling. Other small vessels for crew
	transport and maintenance on site.
Operational	Noise transmitted through the water from operational WTG. The project design envelope gives
WTG	turbines with rotor diameters of up to 305 m.

- 6.1.1.3 Noise from clearing unexploded ordnance (UXO) is also expected, however an assessment of this has not been undertaken as UXO clearance will not be included in the application. A detailed assessment of UXO clearance will be developed for a separate marine licence at a later stage (this approach was agreed with the Marine Management Organisation (MMO) 26 November 2018 see Volume A1, Chapter 4: Project Description).
- 6.1.1.4 In addition, a high-level review of potential noise from decommissioning activities is given in Section 6.4.
- 6.1.1.5 The NPL Good Practice Guide 133 for underwater noise measurements (Robinson et al. 2014) indicates that under certain circumstances, a simple modelling approach may be considered acceptable. Such an approach has been used for these noise sources, which are variously either quiet compared to impact piling (e.g. drilling and cable laying) or where detailed modelling would imply an unwarranted accuracy (e.g. where data is limited such as with large operational WTG noise). The high-level overview of modelling that has been presented is here considered sufficient and there would be little benefit in using a more





detailed model at this stage. The limitations of this approach are acknowledged, including the lack of frequency or bathymetry dependence.

6.2 Noise making activities

- 6.2.1.1 For the purposes of identifying the greatest noise levels, approximate subsea noise levels have been predicted using a simple modelling approach based on measured data from Subacoustech Environmental's own underwater noise measurement database, scaled to relevant parameters for the site and specific noise sources to be used at the site. The calculation of underwater noise transmission loss (TL) for the non-impulsive sources is based on an empirical analysis of the noise measurements taken on transects around these sources by Subacoustech. Many of these are identified as a separate section in the References in Section 8. It uses an N.log R α R principle, fitted to the data.
- 6.2.1.2 Predicted source levels and TL calculations for the construction activities are presented in Table 74 along with a summary of the number of datasets used in each case. As previously, all SEL_{cum} criteria use the same assumptions as presented in Section 2.2.2, and ranges smaller than 50 m (single strike) and 100 m (cumulative) have not been presented. It should be noted that this modelling approach does not take bathymetry or other environmental conditions into account, and as such can be applied to any location in the Hornsea Four project area. Noise from operational WTGs has been reviewed separately in Section 6.3 and decommissioning noise is reviewed in Section 6.4. All RMS values are based on steady-state, continuous, average noise measurements of at least 10 s, and are appropriate for ongoing activities of indeterminate duration. They should not be confused with the exposure metric, SEL, which are accumulative and where the period of exposure is crucial.



Table 74: Summary of the estimated unweighted source levels for the different construction noise sources considered.

Source	Estimated unweighted source level	Approximate TL (N log R - a R)	Comments
Dredging	186 dB re 1 µPa @ 1 m (RMS)	19 log R - 0.0009 R	Based on five datasets from suction and cutter suction dredgers.
Drilling	179 dB re 1 µPa @ 1 m (RMS)	16 log R - 0.0006 R	Based on seven datasets of offshore drilling using a variety of drill sizes and powers.
Cable laying	171 dB re 1 µPa @ 1 m (RMS)	13 log R (no absorption)	Based on 11 datasets from a pipe laying vessel measuring 300 m in length; this is considered a maximum design noise source for cable laying operations.
Rock placement	172 dB re 1 µPa @ 1 m (RMS)	12 log R - 0.0005 R	Based on four datasets from rock placement vessel 'Rollingstone.'
Trenching	172 dB re 1 µPa @ 1 m (RMS)	13 log R - 0.0004 R	Based on three datasets of measurements from trenching vessels more than 100 m in length.
Vessel noise (large)	171 dB re 1 µPa @ 1 m (RMS)	12 log R -0.0021 R	Based on five datasets of large vessels including container ships, FPSOs and other vessels more than 100 m in length. Vessel speed assumed as 12 knots.
Vessel noise (medium)	164 dB re 1 µPa @ 1 m (RMS)	12 log R - 0.0021 R	Based on three datasets of moderate sized vessels less than 100 m in length. Vessel speed assumed as 12 knots.

6.2.1.3 To account for the weightings required for modelling using the Southall et al. (2019) criteria, reductions in source level have been applied to the various noise sources. Figure 25 shows the representative noise measurements used, adjusted for the source levels in Table 74.
 Table 75 presents the details of the reductions in source levels used for each of the weightings used for modelling.

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Figure 25: Summary of the 1/3 octave frequency bands used as basis for the Southall et al. (2019) weightings used in the simple modelling

Table 75: Reductions in the source levels for the different construction noise sources considered when the Southall et alet al. (2019) weightings are applied.

Source	Reduction in source level from the unweighted level					
	LF	HF	VHF	PCW		
Dredging	2.5 dB	7.9 dB	9.6 dB	4.2 dB		
Drilling	4.0 dB	25.8 dB	28.4 dB	13.2 dB		
Cable laying	3.6 dB	22.9 dB	23.9 dB	13.2 dB		
Rock placement	1.6 dB	11.9 dB	12.5 dB	8.2 dB		
Trenching	4.1 dB	23.0 dB	25.0 dB	13.7 dB		
Vessel noise	5.5 dB	34.4 dB	38.6 dB	17.4 dB		

- 6.2.1.4 **Table 76** and **Table 77** summarise the predicted impact ranges for these noise sources. It is worth noting that the Southall et al. (2019) and Popper et al. (2014) criteria give different criteria for non-impulsive or continuous noise sources compared to impulsive noise (see **Section 2.2.2**); all sources in this section are considered non-pulse or continuous-type.
- 6.2.1.5 Given the modelled impact ranges, any marine mammal would have to, in most case, be less than 100 m from the continuous noise sources at the start of the activity to acquire the necessary exposure to induce PTS as per Southall et al. (2019). The exposure calculation assumes the same receptor swim speed as in the previous modelling. It should also be noted that this would only mean that the receptor reaches the 'onset' stage, which is the minimum exposure that could potentially lead to TTS. In most hearing groups, the noise levels are low enough that there is negligible risk.

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6.2.1.6 For fish, there is a low to negligible risk of any injury or TTS, in line with guidance for continuous noise sources in Popper et al. (2014) and presented in paragraph 2.2.2.18 and Table 5. All sources presented here are much quieter than those presented for impact piling in Section 5.

Table 76: Summary of the impact ranges for the different construction noise sources using the non-impulsive criteria from Southall et alet al. (2019) for marine mammals at Hornsea Four.

Sout	hall et alet al.	Dredging	Drilling	Cable	Rock	Trenching	Vessels	Vessels
(201	9)			laying	placement		(large)	(medium)
	199 dB (LE SEL cum)	< 100 m	< 100 m	< 100 m	< 100 m	< 100 m	< 100 m	< 100 m
	198 dB (HF SEL _{cum})	< 100 m	< 100 m	< 100 m	< 100 m	< 100 m	< 100 m	< 100 m
	173 dB (VHF SEL _{cum})	< 100 m	< 100 m	< 100 m	< 100 m	< 100 m	< 100 m	< 100 m
PTS	201 dB (PCW SEL _{cum})	< 100 m	< 100 m	< 100 m	< 100 m	< 100 m	< 100 m	< 100 m
	179 dB (LF SEL _{cum})	< 100 m	< 100 m	< 100 m	< 100 m	< 100 m	< 100 m	< 100 m
	178 dB (HF SEL _{cum})	< 100 m	< 100 m	< 100 m	< 100 m	< 100 m	< 100 m	< 100 m
	153 dB (VHF SEL _{cum})	230 m	< 100 m	< 100 m	990 m	< 100 m	< 100 m	< 100 m
TTS	181 dB (PCW SEL _{cum})	< 100 m	< 100 m	< 100 m	< 100 m	< 100 m	< 100 m	< 100 m

Table 77: Summary of the impact ranges from Popper et alet al. (2014) for shipping and continuous noise, covering the different construction noise sources for species of fish (swim bladder involved in hearing for Hornsea Four.

Popper et alet al. (2014)	Dredging	Drilling	Cable laying	Rock placement	Trenching	Vessels (large)	Vessels (medium)
Recoverable injury 170 dB (48 hours) Unweighted SPL _{RMS}	< 50 m	< 50 m	< 50 m	< 50 m	< 50 m	< 50 m	< 50 m
TTS 158 dB (12 hours) Unweighted SPL _{RMS}	< 50 m	< 50 m	< 50 m	< 50 m	< 50 m	< 50 m	< 50 m

6.3 Operational WTG noise

6.3.1.1 The main source of underwater noise from operational WTGs will be mechanically generated vibration from the rotating machinery in the turbines, which is transmitted into the sea through the structure of the turbine tower, pile and foundations (Nedwell et al. 2003a, Tougaard et al, 2020). Noise levels generated above the water surface are low enough that no significant airborne sound will pass from the air to the water.



6.3.1.2 The project design envelope for Hornsea Four gives the maximum potential WTG rotor diameter as 305 m. A summary of operational WTG where measurements have been collected is given in Table 78.

Wind farm	Lynn	Inner Dowsing	Gunfleet Sands 1 & 2	Gunfleet Sands 3
Type of turbine	Siemens	Siemens	Siemens	Siemens
used	SWT-3.6-107	SWT-3.6-107	SWT-3.6-107	SWT-6.0-120
Number of turbines	27	27	48	2
Rotor diameter	107 m	107 m	107 m	120 m
Water depths	6 to 8 m	6 to 14 m	0 to 15 m	5 to 12 m
Representative	Sandy gravel /	Sandy gravel /	Sand / muddy sand /	Sand / muddy sand /
sediment type	muddy sandy gravel	muddy sandy gravel	muddy sandy gravel	muddy sandy gravel
Turbine separation	500 m	500 m	890 m	435 m
(representative)				

Table 78: Characteristics of measured operational wind farms used as a basis for modelling.

- 6.3.1.3 The estimation of the effects of operational noise in these situations has two features that make it harder to predict compared with noise sources such as impact piling. Primarily, the problem is one of level; noise measurements made at many wind farms have demonstrated that the operational noise produced was at such a low level that it was difficult to measure relative to background noise at distances of a few hundred metres (Cheesman 2016). Secondly, the multiple turbines of an offshore wind farm could be considered as an extended, distributed noise source, as opposed to a "point source" as would be appropriate for pile driving at a single location, for example. The measurement techniques used at the sites above have dealt with these issues by considering the operational noise spectra in terms of levels within and on the edge of the wind farm (but relatively close to the turbines, so that some noise above background could be detected).
- 6.3.1.4 The considered turbine size for modelling Hornsea Four is larger than those for which data is available. Hornsea Four is also situated in greater water depths, and as such, estimations of a scaling factor must be conservative to minimise the risk of underestimating the noise. However, it is recognised that the available data on which to base the scaling factor is limited and the extrapolation that must be made is significant.
- 6.3.1.5 The operational source levels (as SPL_{RMS}) for the measured sites are given in Table 79 (Cheesman 2016), with an estimated source level for Hornsea Four in the bottom row. To predict operational WTG noise levels at Hornsea Four, the level sampled at each of the sites has been taken and then a linear correction factor has been included to scale up the source levels (Figure 26). A linear fit was applied to the data as this was the most conservative extrapolation, leading to the highest, and thus maximum design, estimation of source level noise from the larger 305 m diameter rotor WTGs. This resulted in an estimated source level of 165.4 dB SPL_{RMS} @ 1 m, 19.4 dB higher than the 120 m diameter rotor WTG; the largest for which noise data is currently available.

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Table 79: Measured operational WTG noise taken at operational wind farms, and the predicted source level for the maximum turbine size considered at Hornsea Four.

Site	Unweighted source level
Lynn (107 m)	141 dB re 1 µPa (RMS) @ 1 m
Inner Dowsing (107 m)	142 dB re 1 µPa (RMS) @ 1 m
Gunfleet Sands 1 & 2 (107 m)	145 dB re 1 µPa (RMS) @ 1 m
Gunfleet Sands 3 (120 m)	146 dB re 1 µPa (RMS) @ 1 m
Hornsea Four (305 m)	165.4 dB re 1 µPa (RMS) @ 1 m



Figure 26: Extrapolated source levels from operational WTGs plotted with a linear fit to estimate the source level for a WTG with a rotor diameter of 305 m.

- 6.3.1.6 It is acknowledged that this fit is speculative: the available data is very limited. Newer, larger, direct-drive (gearbox-less) designs tend to be more efficient and losses (e.g. in energy which produces noise and vibration) are significantly reduced. Preliminary measurements of such direct-drive WTGs have been collected off the east coast of the United States (HDR 2019), showing extrapolated source levels of 136 dB re 1 μPa (SPL_{RMS}) @ 1 m for a WTG with a 150 m diameter rotor. Stöber and Thomsen (2021) estimate the direct-drive turbines to be 10 dB quieter than an equivalent gearboxed design. Thus, the linear extrapolation represents a considerably greater noise output and can be considered conservative.
- 6.3.1.7 A summary of the predicted impact ranges is given in **Table 80** and **Table 81**. All SEL_{cum} criteria use the same assumptions as presented in Section 2.2.2, and ranges smaller than 50 m (single strike) and 100 m (cumulative) have not been presented. The operational WTG source is considered a non-impulsive sound by Southall et al. (2019) and a continuous source by Popper et al. (2014). For SEL_{cum} calculations, it has been assumed that the operational WTG noise is present 24 hours a day and that the receptor remains stationary in the vicinity for the duration.



Table 80: Summary of the impact ranges for operational WTGs using the non-impulsive noise criteria from Southall et al. (2019) for marine mammals at Hornsea Four.

Southall et alet al. (2019)		Operational WTG (305 m)
PTS	199 dB (LF SEL _{cum})	< 100 m
	198 dB (HF SEL _{cum})	< 100 m
	173 dB (VHF SEL _{cum})	< 100 m
	201 dB (PCW SEL _{cum})	< 100 m
TTS	179 dB (LF SEL _{cum})	< 100 m
	178 dB (HF SEL _{cum})	< 100 m
	153 dB (VHF SEL _{cum})	< 100 m
	181 dB (PCW SEL _{cum})	< 100 m

Table 81: Summary of the impact ranges for shopping and continuous noise from Popper et alet al. (2014) for operational WTGs for species of fish (swim bladder involved in hearing) at Hornsea Four.

Popper et alet al. (2014)	Operational WTG (305 m)	
Recoverable injury	< 50 m	
170 dB (48 hours) Unweighted SPL _{RMS}		
TTS	< 50 m	
158 dB (12 hours) Unweighted SPL _{RMS}		

6.3.1.8 These results show that, for operational WTGs, any injury risk is minimal. The impact ranges calculated above are greater than those based on the noise levels estimated in Tougaard et al. (2020). Taking both sets of results into account (operational WTG noise and other noise sources related to construction, see Section 6.2), and comparing them to the impact piling results in the Section 5 (specifically Section 5.2), it is clear that noise from impact piling results in much greater levels and impact ranges, and hence should be considered the activity which has the potential to have the greatest effect during the construction and lifecycle of Hornsea Four.

6.4 Decommissioning noise

- 6.4.1.1 Decommissioning noise also needs to be considered even in the light of the expected 35 years of operational life. With present technologies, the following decommissioning techniques have been considered:
 - High-powered water jetting/cutting apparatus; and
 - Grinding or drilling techniques.
- 6.4.1.2 It is also worth noting that by the time Hornsea Four is decommissioned, there are likely to be many more options available for decommissioning.
- 6.4.1.3 Water jetting and grinding techniques would produce noise at a much lower and less intrusive level than impact piling. Decommissioning is anticipated to take approximately five years, about the same duration as expected for construction. Thus, the overall impact is expected to be lower than during the construction phase.
- 6.4.1.4 Only closer to the time of decommissioning, when local marine life is known and understood, can a realistic and useful assessment of the effects of the noise, and the





appropriate mitigation, be carried out. It seems clear that a separate and new impact assessment will be required closer to the time of decommissioning and no further discussion will be made here.

7 Discussion

- 7.1.1.1 This report presents a study presenting the potential levels of underwater noise during the development of Hornsea Four, primarily focussing on impact piling noise as this has been recognised as the activity known to have the greatest potential underwater noise levels.
- 7.1.1.2 The level of underwater noise from the installation of monopiles and pin piles during construction has been estimated using the INSPIRE subsea noise modelling software, which considers a wide variety of input parameters including bathymetry, hammer blow energy and the frequency content of the noise.
- 7.1.1.3 Four representative locations were chosen at Hornsea Four array area and the nearby HVAC location to give spatial variation as well as to consider changes in water depth. At each location four scenarios were considered, covering maximum design and most-likely parameters for installing monopiles and pin piles at each location. The maximum design maximum blow energies used for modelling were 5,000 kJ for monopiles and 3,000 kJ for pin piles. Lower blow energies of 4,000 kJ and 1,750 kJ were used for the most-likely scenarios. The results showed that greater levels of noise are predicted along transects travelling through deeper water.
- 7.1.1.4 The modelling results were analysed in terms of relevant noise metrics and criteria to aid assessments of the impacts from the impact piling noise on marine mammals and fish. Southall et alet al. (2019) was used for various species of marine mammal using unweighted SPL_{peakj} and weighted SEL_{cum} metrics. The largest impact ranges for these criteria are summarised in Table 82. For all cases in the table below, the maximum design modelling parameters at the East location provided the largest impact ranges.

Southall et alet al. (2019) (weighted SEL _{cum})		Maximum design monopile (5,000 kJ)	Maximum design pin pile (3,000 kJ)
РТЅ	Low-frequency cetacean (LF)	ll km	9.2 km
	High-frequency cetacean (HF)	< 100 m	< 100 m
	Very high-frequency cetacean (VHF)	450 m	12 km
	Phocid Carnivore in Water (PCW)	< 100 m	42 km
TTS	Low-frequency cetacean (LF)	42 km	40 km
	High-frequency cetacean (HF)	< 100 m	< 100 m
	Very high-frequency cetacean (VHF)	25 km	42 km
	Phocid Carnivore in Water (PCW)	22 km	19 km

 Table 82: Summary of the maximum predicted impact ranges for marine mammal criteria (E

 location, maximum design parameters).

7.1.1.5 Impact range criteria from Popper et alet al. (2014) was used for various groups of fish, with ranges of up to 1.3 km for recoverable injury (SPL_{peak}) and out to 26 km (fleeing) and 38 km (stationary) for TTS (SEL_{cum}) at the maximum blow energies when considering the maximum design parameters for monopiles.





7.1.1.6 Noise sources other than piling have been considered using a high-level, simple modelling approach, including dredging, drilling, cable laying, rock placement, trenching, vessel noise and operational WTG noise. The predicted noise levels for the other construction noise sources and during WTG operation are well below those predicted for impact piling noise. The risk of any potential injurious effects to fish or marine mammals from these sources are expected to be negligible as the noise emissions from these are very close to, or below, the appropriate injury criteria at the source of the noise. Noise during decommissioning techniques has the potential for an effect, however a separate and new impact assessment will be required once the techniques to be used are understood.

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